

Deliverable D3.5

Proceedings of Breaking the Surface summer school 2

Project Acronym:	EXCELLABUST	
Grant Agreement number:	691980	
Project title:	Excelling LABUST in marine robotics	
Funding:	Horizon2020 Twinning	
Call:	H2020-TWINN-2015	
Type of action:	CSA	
Start date of project:	1 st January 2016	
Duration:	36 months	
Project website:	http://excellabust.fer.hr/	
Delivery date:	31 st October 2017	
Version:	1.0	
Lead participant	UNIZG-FER	
Dissemination level:		
PU	Public	X
CO	Confidential, only for members of the consortium (including the Commission Services)	



This project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No 691980.



DELIVERABLE DATA SHEET

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Work package:		WP3 – Broad networking events			
Type:		Delivery date	31/10/2017	Version:	1.0
Lead participant		University of Zagreb Faculty of Electrical Engineering and Computing (UNIZG - FER)			
Dissemination level:					
PU	Public				X
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Version log			
Revision no.	Date	Author (Partner)	Change

Deliverable summary
<p>The 2nd EXCELLABUST summer school “Breaking the Surface” 2017 (http://bts.fer.hr/) was held from 1st until 8th October in Biograd na Moru, Croatia and more than 190 people participated. The programme was divided in five program tracks: marine robotics (MAROB); marine biology and marine nature protection (MARBIO); maritime security, naval and coast guard operations (MARSEC); maritime, nautical and ship archaeology (MARCH), and this year’s novelty in the programme: Innovation Tuesday programme (INNOVA). In 7 days 29 lectures, 11 demonstrations and 1 tutorial were presented.</p> <p>This deliverable offers report on organization of BtS and its programme. The deliverable is accompanied with appendixes with abstracts, biographies and presentations of the programme presenters:</p> <p><i>APPENDIX I. – Abstracts and biographies</i></p> <p><i>APPENDIX II. – Presentations (slides)</i></p>

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1. INTRODUCTION



The 2nd EXCELLABUST summer school **Breaking the Surface** 2017 was held from 1st until 8th October in Biograd na Moru, Croatia and more than 190 people participated. The programme was divided in six program tracks: marine robotics (MAROB); marine biology and marine nature protection (MARBIO); maritime security, naval and coast guard operations (MARSEC); maritime, nautical and ship archaeology (MARCH); maritime geology (MARGEO) and Innovation Tuesday programme (INNOVA). In 7 days 38 lectures, 10 demonstrations and 5 tutorials were presented.

Dates: 1st – 8th October 2017

Location: Biograd na Moru, Croatia

Website: <http://bts.fer.hr/>

2. REPORT ORGANIZATION

The first part of the report describes the BtS 2017 organization, including the work program. The deliverable is accompanied with appendixes with abstracts, biographies and presentations of the programme presenters:

APPENDIX I. – Abstracts and biographies

APPENDIX II. – Presentations (slides)



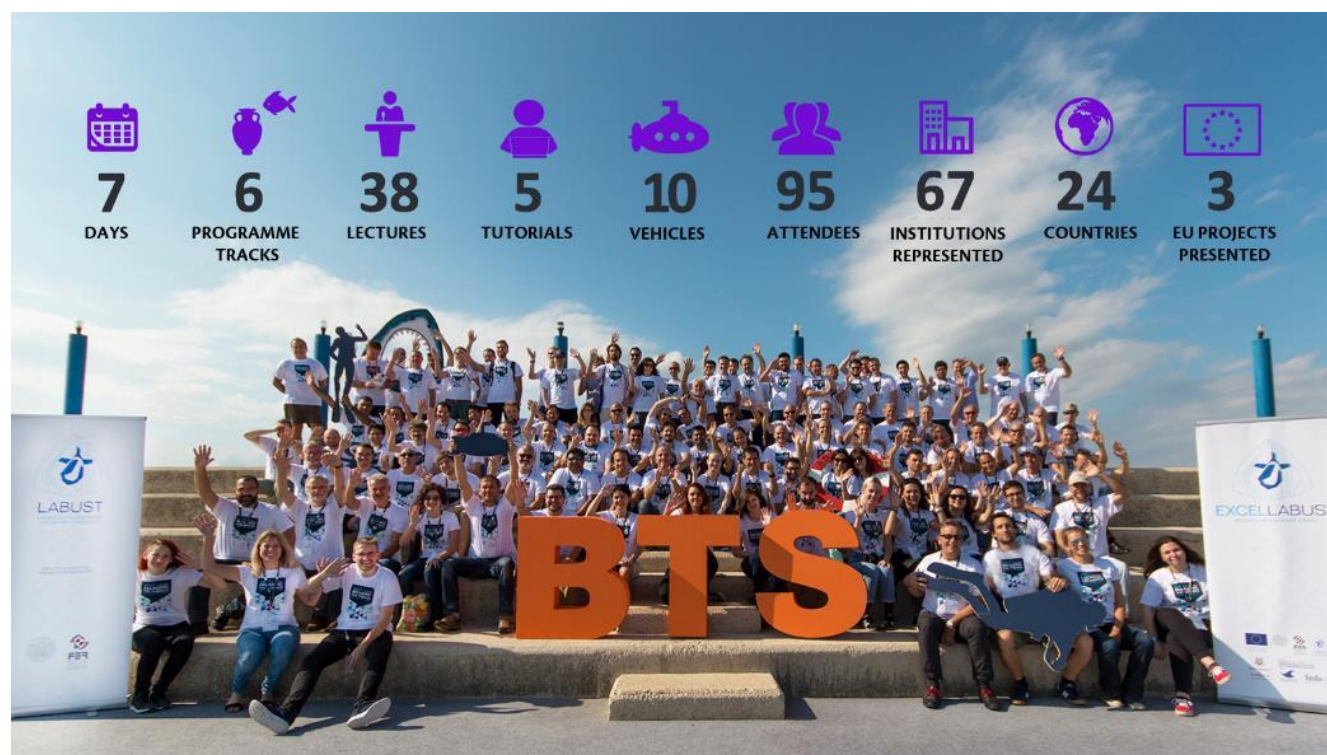
3. ABOUT BREAKING THE SURFACE

Breaking the Surface - BtS summer school has been organized by UNIZG FER LABUST for the last 8 years – first three years as a part of FP7-REGPOT CURE project, while in the following years with Office of Naval Research Global support. During the years, BtS served as a meeting place of experts and students of marine robotics and the marine robotics application areas such as marine biology, marine archaeology, marine security, oceanography, marine geology and oceanology. This is the world's first successful, multi-year field training program that combines academic topics in marine robotics and robotics application areas and hands-on working experience in the sea, doing remote sensing and sampling for various ocean sciences.

Breaking the Surface summer school is organized in attempt to strengthen links between marine robotics research and end-users and provide EXCELLABUST partners with one-week intense summer school consisting of plenary talks, hands-on trainings and demonstrations of marine technologies, by EXCELLABUST partners and worldwide experts.

The program is organized in the form of plenary talks, hands-on tutorials and demonstrations of marine technologies, e.g. marine robotics (MAROB); marine biology and marine nature protection (MARBIO); maritime security, naval and coast guard operations (MARSEC); maritime, nautical and ship archaeology (MARCH), oceanography (OCEAN), and this year's novelty in the programme: Innovation Tuesday programme (INNOVA).

BTS2017 IN NUMBERS:



4. ORGANIZERS

Breaking the Surface summer school is organized under the European Union's Horizon 2020 project EXCELLABUST - Excelling LABUST in marine robotics (GA 691980). The main organizers are University of Zagreb Faculty of Electrical Engineering and Computing, Laboratory for Underwater Systems and Technologies and Centre for Underwater Systems and Technologies with organization support from Institute of Studies on Intelligent Systems for Automation - ISSIA, National Research Council of Italy (CNR), University of Girona (UdG), and University of Limerick (UL).

ORGANIZERS



University of Zagreb



Faculty of Electrical
Engineering and Computing



Laboratory for Underwater
Systems and Technologies



Centre for Underwater
Systems and Technologies

IN PARTNERSHIP WITH



Institute of Studies on Intelligent
Systems for Automation - ISSIA,
National Research Council of Italy
(CNR)



University of Girona (UdG)



University of Limerick (UL)



BREAKING THE SURFACE ORGANIZATION STRUCTURE:

4.1. COMMITTEES CHAIRS



Prof. Dr. Sc. Zoran Vukić
General Chair

*University of Zagreb,
Faculty of Electrical
Engineering and Computing,
Laboratory for Underwater
Systems and Technologies*



**Assoc. Prof. Dr. Sc.
Nikola Mišković**
Programme
Committee Chair
**EXCELLABUST project
Coordinator**

*University of Zagreb,
Faculty of Electrical
Engineering and Computing,
Laboratory for Underwater
Systems and Technologies*



Ivana Mikolić, mag. ing.
Organizing
Committee Chair

*University of Zagreb,
Faculty of Electrical
Engineering and Computing,
Laboratory for Underwater
Systems and Technologies*



**mr. sc. Antonio
Vasiljević,**
Technical Committee Chair

*University of Zagreb,
Faculty of Electrical
Engineering and Computing,
Laboratory for Underwater
Systems and Technologies*

4.2. PROGRAMME COMMITTEE



Marco Bibuli, PhD

*Centre Nazionale delle
Ricerche - CNR
Institute of intelligent systems
for automation - ISSIA*



**Prof. Bridget Buxton,
PhD**

*University of Rhode Island,
Department of History*



Massimo Caccia, MSc

*Centre Nazionale delle
Ricerche - CNR
Institute of intelligent systems
for automation - ISSIA*



**Assoc. Prof. Marc
Carreras, PhD**

*University of Girona
Computer Vision and Robotics
Research Institute - VICOROB*



Damjan Miklić, PhD

*University of Zagreb,
Faculty of Electrical
Engineering and Computing,
Laboratory for Underwater
Systems and Technologies*



Edin Omerdić, PhD

University of Limerick



**Asst. Prof. Dr. Sc. Irena
Radić-Rossi**

*University of Zadar,
Department of Archaeology*



Prof. Pere Ridao, PhD

*University of Girona
Computer Vision and Robotics
Research Institute - VICOROB*



**Prof. Asgeir Sørensen,
PhD**

*Norwegian University of
Science and Technology
Department of Marine
Technology
Centre for Autonomous
Marine Operations and
Systems*



Prof. Daniel Toal, PhD

University of Limerick

4.3. ORGANIZING COMMITTEE



Tonko Bogovac

CUST



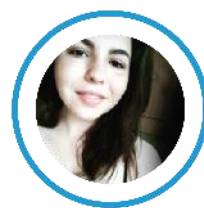
Marija Havačić

CUST



Barbara Klier

CUST



Ena Lucija Kovač

CUST



Petra Kovačević

CUST



Andrea Radmanić

CUST



Alan Vukić

CUST



Valentino Žinić

CUST

4.4. TECHNICAL COMMITTEE



Anja Babić, mag. ing.

UNIZG FER LABUST



Nadir Kapetanović, mag. ing.

UNIZG FER LABUST



Ivan Lončar, mag. ing.

UNIZG FER LABUST



Filip Mandić, mag. ing.

UNIZG FER LABUST



Milan Marković

UNIZG FER LABUST



Đula Nađ, dipl. ing.

UNIZG FER LABUST



M. Eng. Marin Stipanov

UNIZG FER LABUST



Kruno Zubčić

*Croatian Conservation
Institute*

5. PROGRAMME

5.1. PROGRAMME STRUCTURE

BtS program is comprised of academic lectures, hands-on tutorials, presentation of projects and equipment and company demonstrations.



5.1.1. LECTURES

Lectures by experts in the domains of:



marine robotics
MAROB



marine biology
MARBIO



maritime
archaeology
MARCH



maritime
security
MARSEC



marine
geology
MARGEO



Innovations and
entrepreneurships
INNOVA

List of speakers:

Marine robotics (MAROB):

- **Marc Carreras**, Computer Vision and Robotics Institute of the Universitat de Girona (ViCOROB/UdG): *Towards persistent AUVs for seabed inspection*
- **Jeremi Gancet**, Space Applications Services: *DexROV: 2017 trials results and perspectives*
- **William Kirkwood**, Monterey Bay Aquarium Research Institute: *FOCE – Long Term In Situ Ocean Acidification Instrumentation*
- **Nikola Mišković**, University of Zagreb Faculty of Electrical Engineering and Computing: *Human-robot interaction under water*
- **Eduardo Silva**, INESC TEC / ISEP: *Localization and mapping in dynamic underwater environments*
- **Kimón P. Valavanis**, University of Denver: *Navigation and Control of Unmanned Vehicles: A Fuzzy Logic Perspective*

Marine biology (MARBIO):

- **Renee E. Bishop Pierce**, Pennsylvania State University: *Subterranean Groundwater Discharge and Marine Ecosystems*
- **Draško Holcer**, Croatian Natural History Museum / Blue World Institute of Marine Research and Conservation: *Cetaceans and sea turtles of the Adriatic – the next step*
- **Craig R. Smith**, University of Hawaii at Manoa: *Extreme seafloor ecology: use of ROVs and AUVs to evaluate biodiversity and ecosystem function in the world's most remote ecosystems*

Marine archaeology (MARCH):

- **Guillermo de Anda**, Instituto Nacional de Antropología e Historia / National Geographic Society / Proyecto Gran Acuífero Maya: *The Great Maya Aquifer*
- **Andreas Kallmeyer Bloch**, The Viking Ship Museum in Roskilde: *Technology, archaeology and student challenges Finding a best practice for presenting maritime archaeology*
- **A. Harun Özdaş**, Dokuz Eylül University Institute of Marine Science and Technology: *Shipwrecks discovered along the western coast of Turkey*
- **Irena Radić Rossi**, University of Zadar:
- **Augusto Salgado**, CINAV - Centro de Investigação Naval: *Contemporary Underwater Archaeology in Portugal. New challenges, new ideas*
- **Kotaro Yamafune**, A.P.P.A.R.A.T.U.S. LLC & **Matko Čvrlijak**, Roskilde Viking Ship Museum: *A Methodology for Accurate and Quick Photogrammetric Recording of Underwater Cultural Heritage*

Maritime security (MARSEC):

- **Richard J. Nagle**, Naval Sea Systems Command/PMS-408; Navy EOD Program Support Senior Program Analyst, G2 Software Systems, Inc.: *Relevance of UMS for Below the Surface (BTS) Tasks*
- **John Potter**, NATO STO Centre for Maritime Research and Experimentation (CMRE): *Ex Machina – Integrating maritime robots into human endeavours*

Maritime geology (MARGEO):

- **Slobodan Miko**, Croatian Geological Survey: *Late Quaternary and Holocene Submerged Landscapes of the Eastern Adriatic Sea*
- **Javier Escartin**, CNRS/IPGP: *Breaking the surface of the seafloor: Studying the traces of earthquakes underwater*

Innovation Tuesday (INNOVA):

- **Alex Alspach**, Toyota Research Institute: *Soft Sensing and Simulation*
- **Marin Bek**, UNIZG FER / H2O Robotics: *Breaking the corporate*
- **Fabio Bruno**, University of Calabria: *From research to business: some experiences at the University of Calabria*
- **Thomas Curtin**, Applied Physics Laboratory, University of Washington: *The Scaling of Innovation Tools*
- **Cesare Fantuzzi**, University of Modena and Reggio Emilia: *Bridging the gap between academic research and commercially viable technology*
- **Vladimir de Franceschi**, Founder Institute, Inc.: *Startup How To*
- **Gerardo Morales-Hierro**, Triple Helix Venture Capital: *Financing of Early Stage Technology Startups*
- **Vlatka Petrović**, University of Zagreb: *Paths to market – getting university innovation into the right hands*
- **Tom Runge**, German Research Center for Artificial Intelligence DFKI, Robotics Innovation Center: *Rich & Famous with Underwater Robotics? Attempt of an objective assessment*
- **Martina Schraudner**, Fraunhofer Center for Responsible Research and Innovation: *Uncovering the impact of the institutional environment on transfer activities*

5.1.2. TUTORIALS

- **H2020 EXCELLABUST project: Omnidirectional Vision for Underwater Robots** by Nuno Gracias, Ricard Campos, Computer Vision and Robotics Institute of the Universitat de Girona (VICOROB/UdG)
- **H2020 EXCELLABUST project: Parallel Computing with CUDA made (almost) simple** by Matija Rossi, University of Limerick
- **H2020 EXCELLABUST project: POP ART (PORTable Pelagic Autonomous Robotic Technology) concept & field demonstration** by Massimo Caccia, Marco Bibuli, Gabriele Bruzzone, Angelo Odetti, Consiglio Nazionale delle Ricerche – Istituto di Studi sui Sistemi Intelligenti per l'Automazione
- **H2020 DexROV project: Teleoperation of a simulated ROV and arm** by Gianluca Antonelli, ISME / University of Cassino
- **Underwater Camera Calibration with the Pinax model** by Andreas Birk, Tomasz Łuczyński, Jacobs University Bremen, Robotics Group

5.1.3.DEMONSTRATIONS

- **H2020 DexROV project: Experiencing and mitigating latency in remote ROV operations** by Jeremi Gancet, Space Applications Services
- **H2020 DexROV project: Dexterous manipulation** by Alessio Turetta, Graal Tech
- **H2020 subCULTron project - first swarm tests** by Tamara Petrović, Barbara Arbanas, Anja Babić, Ivan Lončar, Milan Marković, Goran Vasiljević, University of Zagreb Faculty of Electrical Engineering and Computing

5.1.4.COMPANY PROGRAMME

- **BluEye Robotics** by Martin Ludvigsen, Sindre Hansen
- **Blueprint subsea** by Robin Sharphouse, Kevin Webster
- **EvoLogics** by Konstantin Kebkal, Oleksiy Kebkal
- **NORBIT Subsea** by Thomas Rygh



5.2. SCHEDULE

	MONDAY 02.10.	TUESDAY 03.10.	WEDNESDAY 04.10.	THURSDAY 05.10.	FRIDAY 06.10.	
09:00 - 09:45	OPENING SESSION <i>Mislav Grgić, Zoran Vukić, Nikola Mišković</i>	Startup How To <i>Vladimir de Franceschi</i>	Localization and mapping in dynamic underwater environments <i>Eduardo Silva</i>	FOCE – Long Term In Situ Ocean Acidification Instrumentation <i>William Kirkwood</i>	Ex Machina – Integrating maritime robots into human endeavours <i>John Potter</i>	
09:45 - 10:30	Human-robot interaction under water <i>Nikola Mišković</i>	The Scaling of Innovation Tools <i>Thomas Curtin</i>	Technology, archaeology and student challenges: Finding a best practice for presenting maritime archaeology <i>Andreas Kallmeyer Bloch</i>	Extreme seafloor ecology: use of ROVs and AUVs to evaluate biodiversity and ecosystem function in the world's most remote ecosystems <i>Craig R. Smith</i>	Subterranean Groundwater Discharge and Marine Ecosystems <i>Renee E. Bishop Pierce</i>	
10:30 - 10:45	COFFEE BREAK	COFFEE BREAK	COFFEE BREAK	COFFEE BREAK	COFFEE BREAK	
10:45 - 11:30	Shipwrecks discovered along the western coast of Turkey <i>A. Harun Özdağ</i>	Rich & Famous with Underwater Robotics? Attempt of an objective assessment <i>Tom Runge</i>	Relevance of UMS for Below the Surface (BTS) Tasks <i>Richard J. Nagle</i>	Late Quaternary and Holocene Submerged Landscapes of the Eastern Adriatic Sea <i>Slobodan Miko</i>	Navigation and Control of Unmanned Vehicles: A Fuzzy Logic Perspective <i>Kimon P. Valavanis</i>	
11:30 - 12:15	DexROV: 2017 trials results and perspectives <i>Jeremi Gancet</i>	Paths to market – getting university innovation into the right hands <i>Vlatka Petrović</i>	Cetaceans and sea turtles of the Adriatic – the next step <i>Draško Holcer</i>	Contemporary Underwater Archaeology in Portugal. New challenges, new ideas <i>Augusto Salgado</i>	Breaking the surface of the seafloor: Studying the traces of earthquakes underwater <i>Javier Escartin</i>	
12:15 - 13:00	A Methodology for Accurate and Quick Photogrammetric Recording of Underwater Cultural Heritage <i>Kotaro Yamafune</i>	Financing of Early Stage Technology Startups <i>Gerardo Morales-Hierro</i>	The Great Maya Aquifer <i>Guillermo de Anda</i>	Towards persistent AUVs for seabed inspection <i>Marc Carreras</i>	COMPANY PRESENTATION Evolgics	
13:00 - 14:30	LUNCH	LUNCH	LUNCH	LUNCH	LUNCH	
14:30 - 15:00	COMPANY PRESENTATION BlueEye Robotics	Breaking the corporate <i>Marin Bek</i>	T2 intro: Parallel Computing with CUDA made (almost) simple <i>University of Limerick</i>	COMPANY PRESENTATION Norbit	COMPANY PRESENTATION Blueprint subsea	
15:00 - 15:30	T1 intro: Omnidirectional Vision for Underwater Robots <i>University of Girona</i>	Soft Sensing and Simulation <i>Alex Altpach</i>	T3 intro: Underwater Camera Calibration with the Pinax model <i>JACOBS Bremen</i>	T4 intro: Teleoperation of a simulated ROV and arm <i>ISME</i>	T5 intro: POP ART (POrtable Pelagic Autonomous Robotic Technology) concept & field demonstration <i>CNR</i>	
15:30 - 16:00	DEMO subCULTron Group 1	T1 hands-on Group 2	DEMO Blueeye Group 3	DEMO subCULTron Group 2	T1 hands-on Group 2	DEMO Blueeye Group 3
16:00 - 16:30	DEMO subCULTron Group 2	T1 hands-on Group 3	DEMO Blueeye Group 1	DEMO subCULTron Group 3	T1 hands-on Group 3	DEMO Blueeye Group 1
16:30 - 16:45	COFFEE BREAK					
16:45 - 17:30	DEMO subCULTron Group 3	T1 hands-on Group 1	DEMO Blueeye Group 2	DEMO subCULTron Group 1	T1 hands-on Group 1	DEMO Blueeye Group 2
17:30 - 18:00	DEMO subCULTron Group 1	T1 hands-on Group 2	DEMO Blueeye Group 3	DEMO subCULTron Group 2	T1 hands-on Group 2	DEMO Blueeye Group 3
18:00 - 18:30	DEMO subCULTron Group 2	T1 hands-on Group 3	DEMO Blueeye Group 1	DEMO subCULTron Group 3	T1 hands-on Group 3	DEMO Blueeye Group 1

SESSION COLORS

Lectures
Innovation Tuesday
Social events
Company programme
Tutorial
Demonstration

LECTURE CATEGORIES:

MAROB	MARSEC	COMPANY PRESENTATION
MARBO	MARCEO	
MARCH	INNOVA	

LOCATIONS:

LECTURES HALL @ HOTEL ADRIATIC (PURPLE) Programme: All lectures and presentations	TUTORIAL ROOM @ HOTEL ADRIATIC (PURPLE) Programme: tutorials, master plans, data analysis	DELIVERY BAR Social events: BTS Karaoke, Excellabust Party
DEMO POOL & OPEN WATERS NEARBY Programme: equipment demonstrations	LAVENDER BAR @ HOTEL ADRIATIC (PURPLE) Programme: Welcome Drink	



REGISTRATIONS

Sunday, 1.10.
16:30 – 18:00



KARAOKE NIGHT

Thursday, 5.10.
21:00 – 0:00



WELCOME DRINKS

Sunday, 1.10.
18:00 – 19:30



CLOSING CEREMONY GALA DINNER

Friday, 6.10.
19:30 – 21:00



NORWEGIAN PARTY

Monday, 2.10.
20:30 – 0:00



HAWAII POOL PARTY

Friday, 6.10.
21:00 – 0:00



EXCELLABUST PARTY

Tuesday, 3.10.
21:00 – 0:00



FIELD TRIP

Saturday, 7.10.
8:00 – 16:00

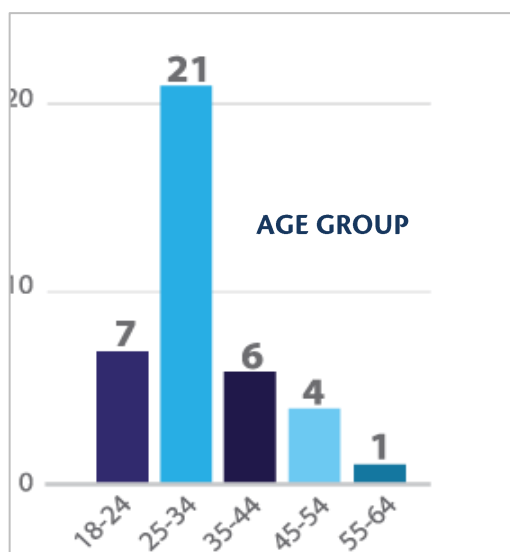
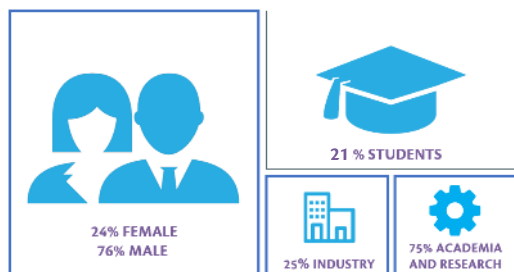


6. BTS PARTICIPANTS

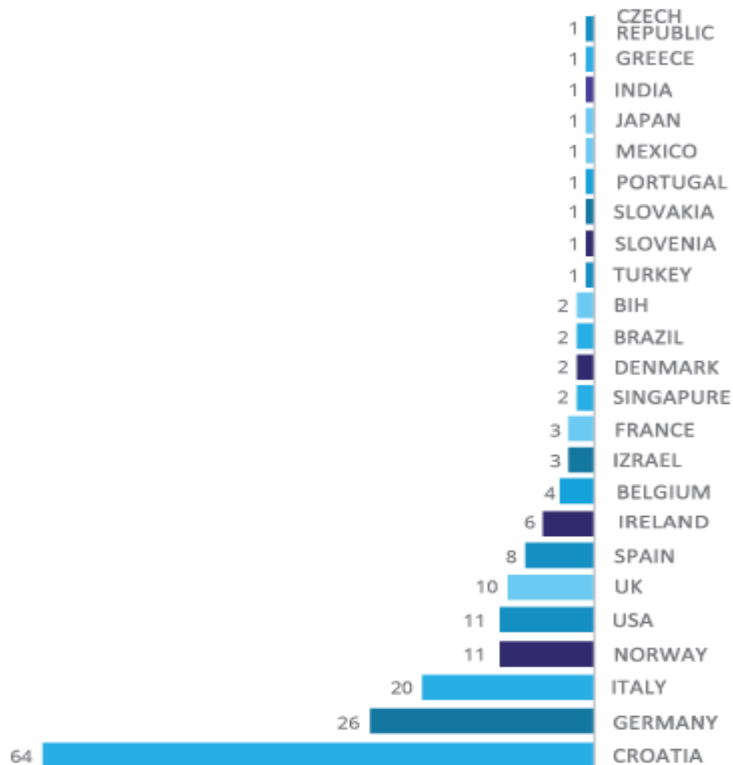
In 2017, 192 participants from academia and industry from various fields joined Breaking the Surface.



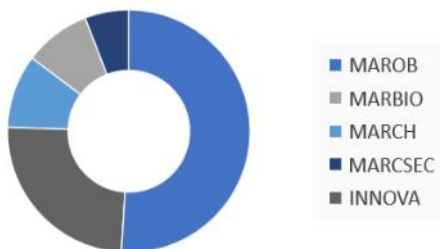
PARTICIPANTS PROFILE



24 COUNTRIES



FIELD OF WORK



4,88

OVERALL
GRADE BY
PARTICIPANTS

92%

WOULD
COME BACK
NEXT YEAR
(REST MAYBE)

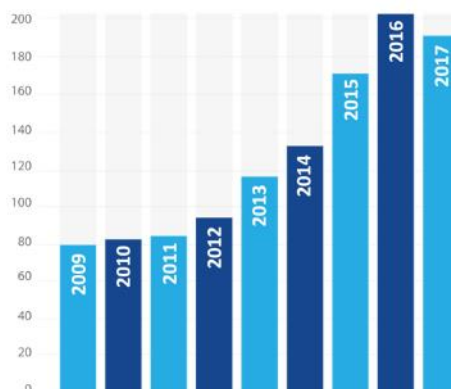
93%

PEOPLE HEARD ABOUT
BTS THROUGH
PERSONAL
RECOMMENDATION



TESTIMONIALS

**BTS
THROUGH
YEARS
WE
KEEP
ON
GROWING**



BTS 2017 TESTIMONIALS

Keep up the good work! :D
Another excellent year! Great job :D
It was awesome! Best organizing team ever!
Just keep up the good work!!

Great parties! Keep them coming!
10/10 would come again
What an amazing event!
Best conference I've ever been to!



REASONS TO ATTEND:

- Knowledge and Collaborations
- Great opportunity to come in touch with many experts in the field of marine sciences
- Because it is a great combination of lectures, workshops and demonstrations from maritime fields. And for me, big plus was innovation day!
- Because it provided a great opportunity to inform students and engineers about the technology needs for studying and monitoring the deep sea, i.e., the largest and most pristine ecosystems in the biosphere
- Because it's awesome!
- Friend told me it's the best conference ever
- BtS each year brings together the most important research groups and companies from the field of marine robotics existing in the world today. BtS gives me the opportunity to get to know them, listen to their work in person and all that in a friendly and relaxed atmosphere. Further, due to great facilities available, BtS allows for on-site testing and demonstrations of equipment.



7. PROGRAMME ABSTRACTS, BIOGRAPHIES AND PRESENTATIONS

Lectures' abstracts and lecturers' biographies are available in **APPENDIX I. – Abstracts and biographies**.
Slides from presentations are available in **APPENDIX II. – Presentations (slides)**.

8. SUPPORTERS

FINANCED BY



Financed in the scope of project EXCELLABUST - Excelling LABUST in marine robotics (GA 691980) which has received funding from the European Union's Horizon 2020 research and innovation programme.

SUPPORTED BY



Embassy of the United States Zagreb
– Croatia



Norwegian Embassy



Foundation of the Croatian Academy
of Sciences and Arts – HAZU

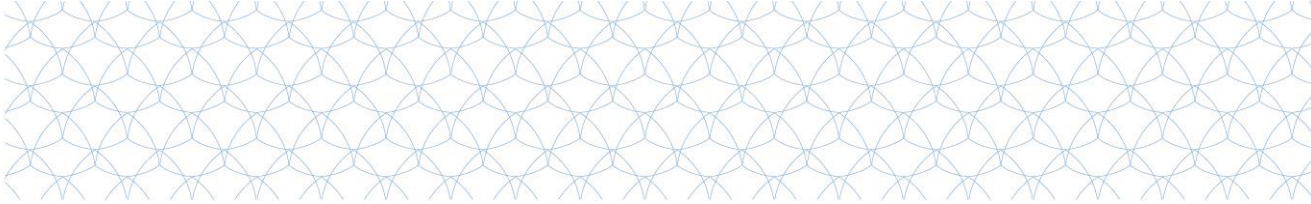


Križevačka Pivovara



Rakije Perković





9. APPENDIX I – ABSTRACTS AND BIOGRAPHIES

Abstracts and biographies are available [here](#).

10. APPENDIX II – PRESENTATIONS

Presentations are available [here](#).

